Technical data Piling and drilling rig







Dimensions Basic machine LRB 125



Technical Data

Leader length 12	.8	m
Capacity: hammer including cap plus pile Max. hammer weight Max. pile weight Max. pull Max. torque1	12 - 6 - 6 20	t t t kNm
Working radius machine Center of rotation – center pile — 3.36 – 5.	56	m
Stepless rig inclination adjustment Lateral inclination — +/-1: Forward inclination — 7 Backward inclination — 7	20 :6 :3	
Vertical leader adjustment above ground level (depending on radius)+/-9	- 5 0º	m

Operating weight and ground pressure

Standard undercarriage with
600 mm 3–web shoes — 44.0 t – 0.95 kg/cm ²
Telescopic undercarriage with 700 mm 3–web shoes 48.0 t $-$ 0.81 kg/cm^2
The operating weight includes the basic machine LRB 125 (leader length 12.8 m, with attachment). Weights can vary depending on the final configuration of the machine.

Transport weight

Without attachment	39.0 t
Without attachment, with telescopic undercarriage	43.0 t

Pile driving equipment Technical data





Vibrator variable moment

Static moment	0-19	kgm
Max. speed	- 2300	rpm
Max. centrifugal force	- 1100	kN
Weight without clamp	_ 3100	kg
Dynamic weight incl. clamp	- 3900	kg
Max. amplitude	0-19	mm

Hydraulic hammer

Max. rated energy free fall4	C	kNm
Max. rated energy with acceleration5	C	kNm
Min. energy	4	kNm
Blow rate max. energy: 50 blows/min Max. blow rate: 85 blows/min		

Drilling equipment



Bouhl		
DOUBI	e rotary	ariiing

Drilling drive I – torque –	– 1 st gear —— 79 kNm - 2 nd gear — 39.5 kNm
Drilling drive I – speed	– 1 st gear ——18 rpm - 2 nd gear — 36 rpm
Drilling drive II – torque –	– 1 st gear — 59 kNm - 2 nd gear 29.5 kNm
Drilling drive II – speed –	– 1 st gear —— 25 rpm - 2 nd gear —— 50 rpm
Max. drilling diameter	700 mm

g	avger drilling	flight	Continuous
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Drilling drive – torque –	1 st dear 1	23 kNm
Drilling drive encod	191	45
Drilling drive – speed –	1st gear	45 rpm
Max drilling diameter	800 m	nm
Max. unining ulameter -		

Technical description



Water-cooled, V 8 cylinder Liebherr diesel engine, model

D 9408 TI–E, turbocharged with intercooler, power rating according to ISO 9249 : 400 kW (544 HP) at 1900 rpm.

The automatic limiting load control adapts perfectly the power of the main users to the present engine speed.

Fuel tank: 870 I capacity with continuous level indicator and reserve warning.



The main pumps are operated by a distributor gearbox. Axial piston displacement pumps work in open circuits supplying oil only when needed (flow control on demand).

The hydraulic pressure peaks are absorbed by the integrated automatic pressure compensation, which relieves the pump and saves fuel.

Pump for working tools:	2x 300 l/min
Separate pump for kinematics:	
Hydraulic oil tank:	825
Max. working pressure:	350 bar

No auxiliary power packs are required as application specific hydraulics supply power to all components.

The cleaning of the hydraulic oils occurs via an electronically monitored pressure and return filter.

Any clogging is shown on the display in the cab.

The use of synthetic environmentally friendly oil is also possible.



Consists of single row ballbearing, fixed axial piston hydraulic motor, spring loaded and hydraulically released multi–disc holding brake, planetary gearbox and pinion.

Free swing with hydraulic moment control reduces wear to a minimum, because rotation moment is sustained through the hydraulic system by the diesel engine.

Swing speed from 0-4.5 rpm is continuously variable.



The control system – developed and manufactured by Liebherr – is designed to withstand extreme temperatures and the many heavy–duty construction tasks for which this machine has been designed. Complete machine operating data are displayed on a high resolution monitor screen.

To ensure clarity of the information on display, different levels of data are shown in enlarged lettering and symbols. Control and monitoring of the sensors are also handled by this high technology system.

Error indications are automatically displayed on the monitor in clear text. The crane is equipped with proportional control for all movements, which can be carried out simultaneously.

The "Redundant" control system allows restricted operation of the machine in the event of a failure on the electronic base control or its sensors.

Two joysticks are required for operation. Pedal control can be changed to hand control.

Options :

- PDE : Process data recording
 - GSM modem



Propulsion through axial piston motor, hydraulically

released spring loaded multi-disc brake, maintenance free crawler tracks, hydraulic chain tensioning device.

Standard undercarriage:	0 _ 1,8 km/h
3-web track shoes:	600 mm
Track force:	336 kN
Telescopic undercarriage:	0 – 2,3 km/h
3-web track shoes:	700 mm



Noise emissions correspond with 2000/14/EC directive on noise emission by equipment used outdoors.

Auxiliary winch

Line pull (nominal load):	50 kN
Bone diameter:	17 mm
Drum diameter	17 mm
Drum diameter.	

The winches are noted for their compact, easily mounted design. Propulsion is via a maintenance free planetary gearbox in oil bath. Load support by the hydraulic system; additional safety factor by a spring–loaded, multi–disc holding brake.



Crowd force push/pull:1	50/200	kN
ine pull (nominal load):		kΝ
Bone diameter:	20	mm
The repeated are actuated by a new orful by draulia avlinder.	20	
The topes are actuated by a powerful hydraulic cyllinder.		

PDE – Process data recording (Additional equipment) This module constantly calculates and stores the current working processes.

Measurements

Measurements are constantly calculated during the working process.

No special measuring process is required. External systems can also be connected to the system.

Display of measurement data

Measurement data relevant to the working process is displayed on the monitor in the cab.

The operator can then control the process and, if necessary, correct it.

Working process interruption

The working process and the measurement can be interrupted at any time.

The measurements are automatically continued upon resumption of work.

Storage of measurement and machine data

All data is stored on a memory card. This can be read via a PC. Thereby an evaluation and processing of data can also be performed at a later time. For example, for:

- client certifications
- conveying daily production data, down time, etc.
- Soil condition report

Printing data

A protocol can be printed out from the cab printer after each working process.

Data transmission

A GSM modem can be connected to the PDE making long distance data transmission possible.



Example of a protocol (in required language):

Spundwand Protokoll auf Bagger





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